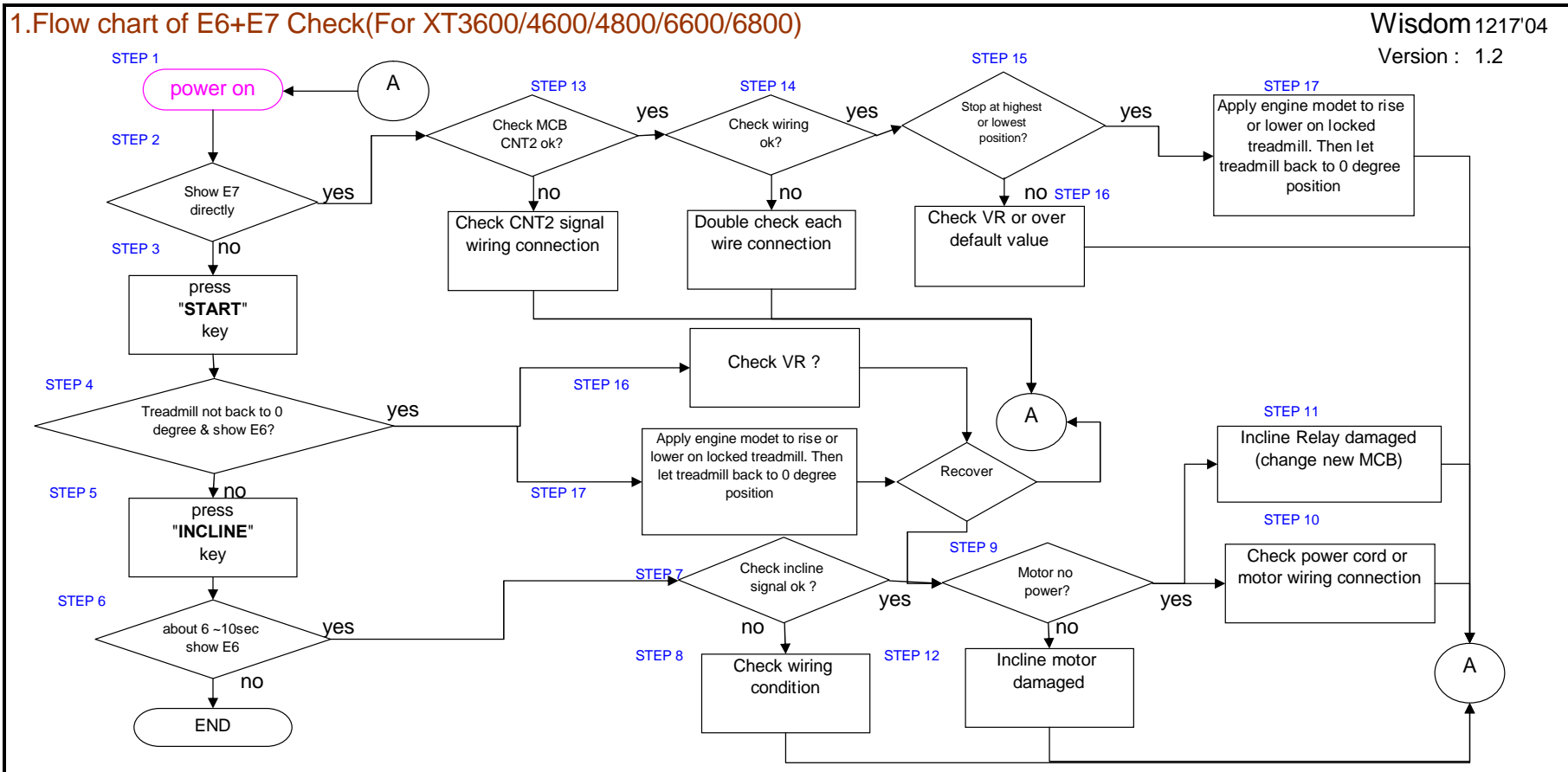


Treadmill Trouble Shooting Guide(Error code check eliminate)

Error code = E6+E7

1.Flow chart of E6+E7 Check(For XT3600/4600/4800/6600/6800)

Wisdom1217'04
Version : 1.2



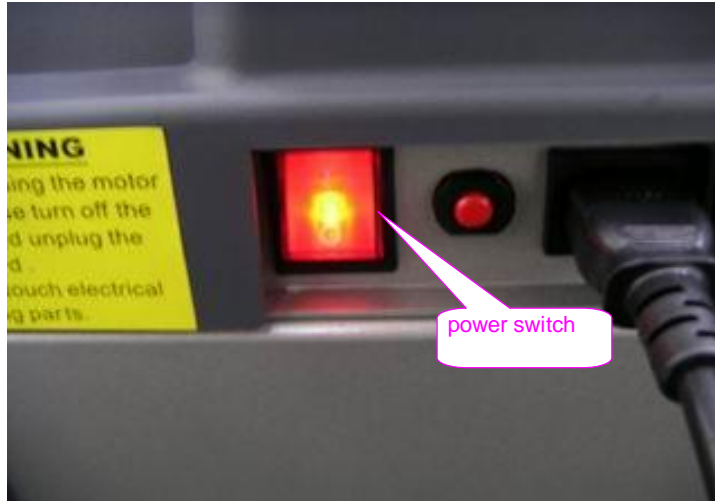
Treadmill Trouble Shooting Guide(Error code check eliminate)

*Explanation

STEP 1 : Power on---

Power switch on , lights on & upper board reacts.

[RETURN](#)



STEP 2 : After 6~10 sec shows "E7".

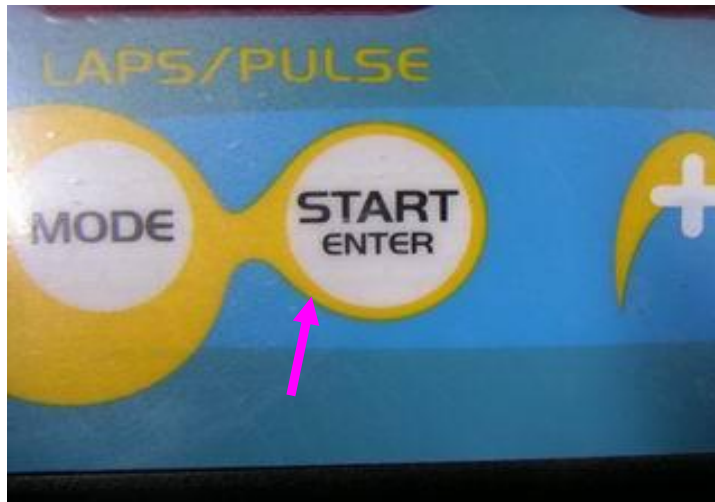
(Different location shows in different model.)

[RETURN](#)



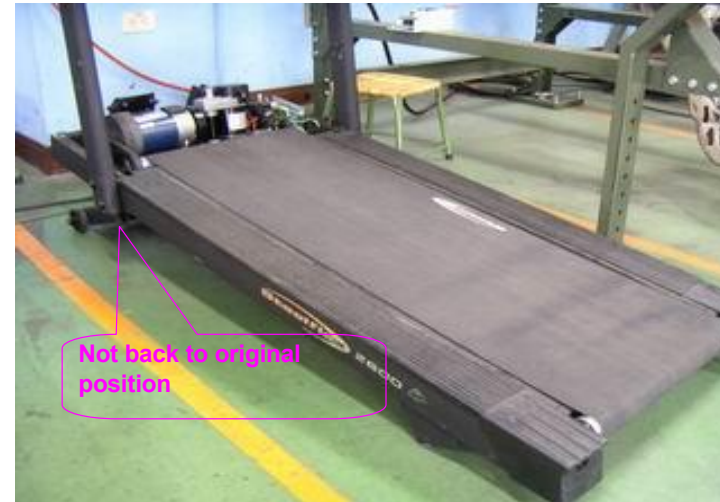
STEP 3 :Push "START" to begin work out.

[RETURN](#)



STEP 4 :Push "INCLINE", treadmill no react .

[RETURN](#)



Treadmill Trouble Shooting Guide(Error code check eliminate)



Treadmill Trouble Shooting Guide(Error code check eliminate)

STEP 5 :Push INCLIN "+" or "--" to adjust inclination.

[RETURN](#)



STEP 6 : After 6~10 sec shows "E6".

(Different location shows in different model.)

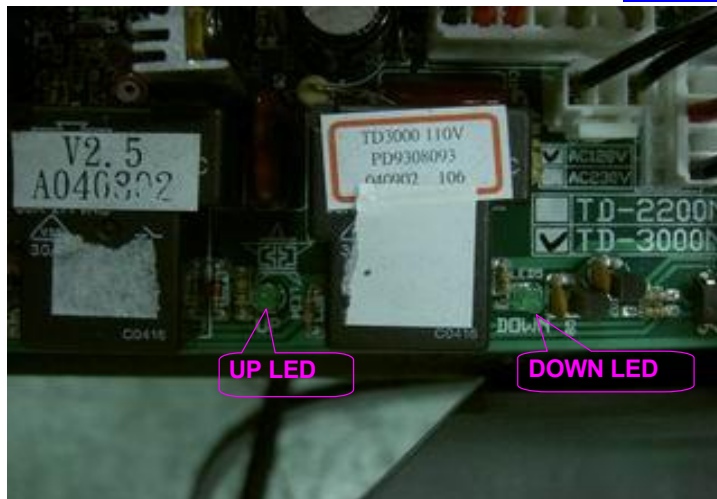
[RETURN](#)



STEP 7 : Check incline signal

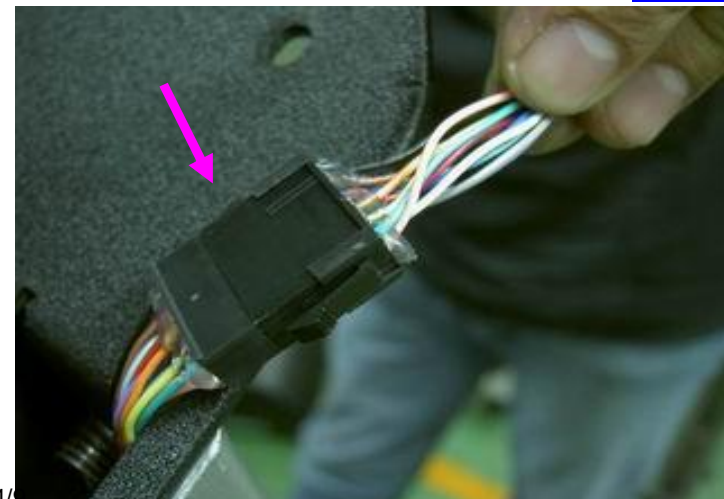
(Incline - UP LED on , decline - DOWN LED on)

[RETURN](#)

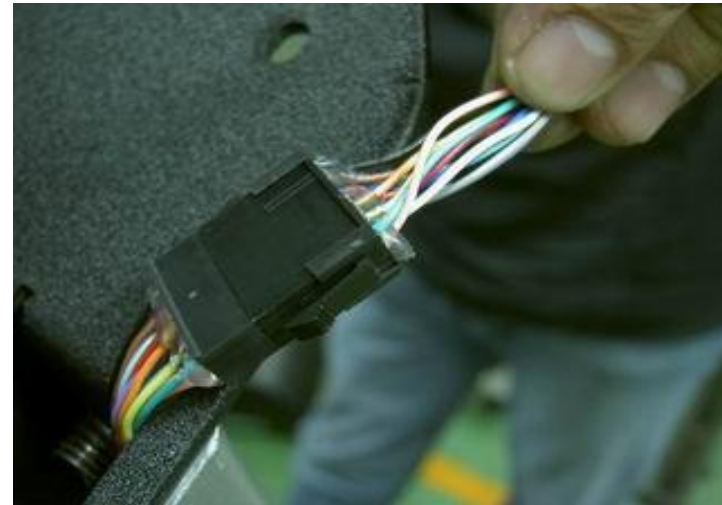


STEP 8 : Check upper & lower wiring connection.

[RETURN](#)



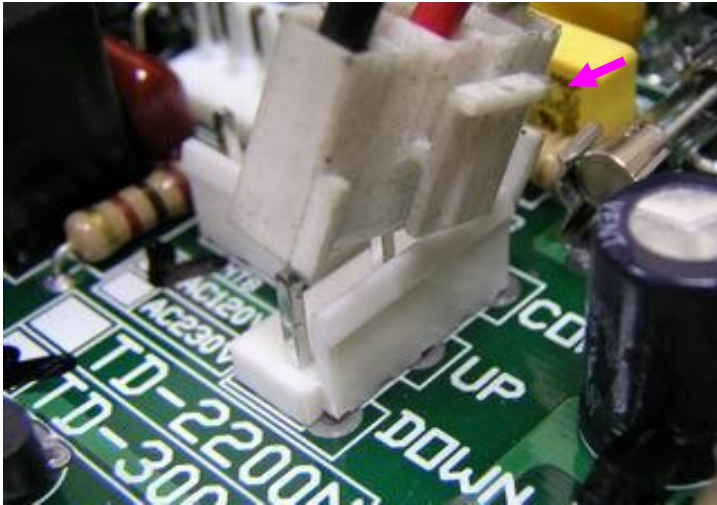
Treadmill Trouble Shooting Guide(Error code check eliminate)



Treadmill Trouble Shooting Guide(Error code check eliminate)

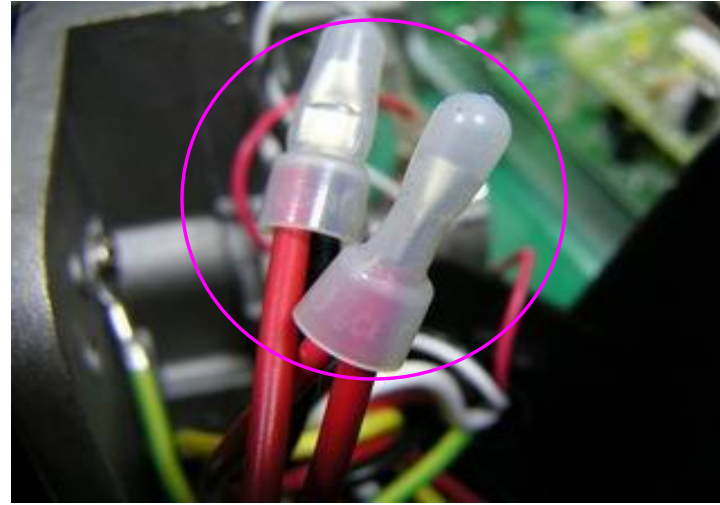
STEP 9 : Check incline motor powercord connection.

[RETURN](#)



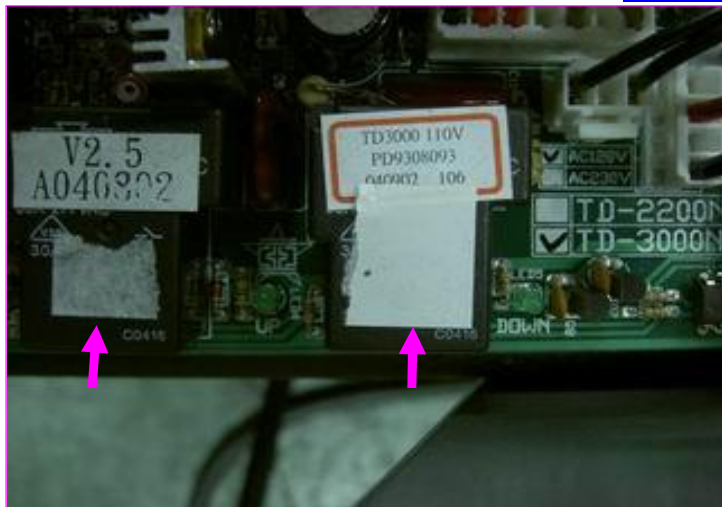
STEP 10 : Check incline motor powercord or check terminal connection as below picture.

[RETURN](#)



STEP 11 : Inclination Relay damaged . Change new MCB.

[RETURN](#)



STEP 12 : Incline motor damaged , change new one.

[RETURN](#)

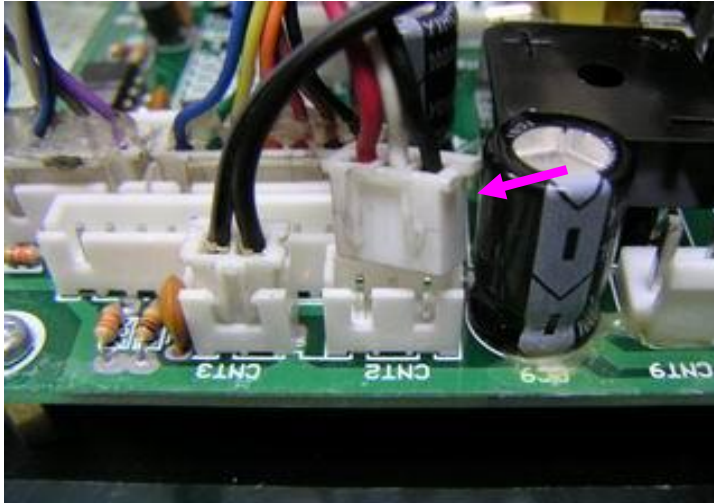


Treadmill Trouble Shooting Guide(Error code check eliminate)

Treadmill Trouble Shooting Guide(Error code check eliminate)

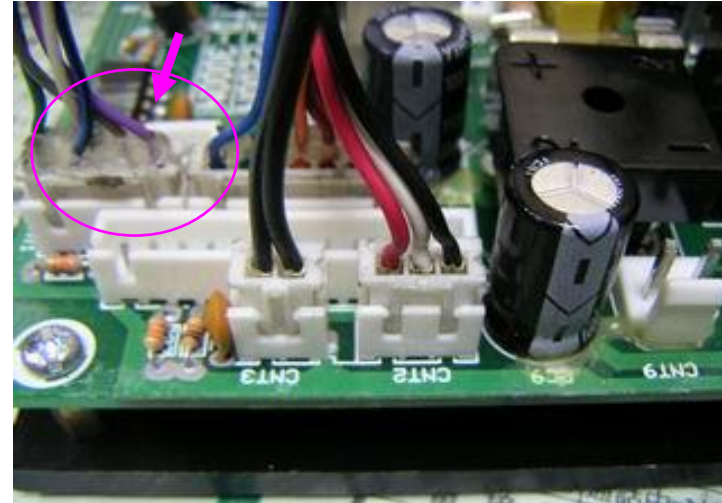
STEP 13 : CNT2 on MCB -bad connection .

[RETURN](#)



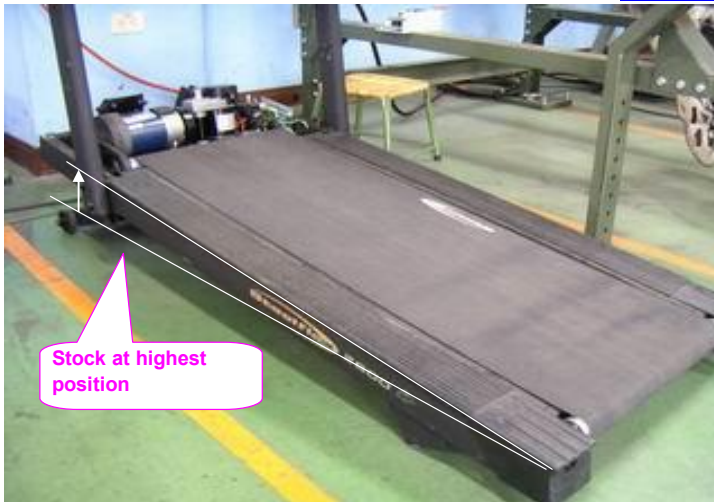
STEP 14 :Check CNT1 connection on MCB.

[RETURN](#)



STEP 15 : Treadmill stops at highest or lowest position.

[RETURN](#)



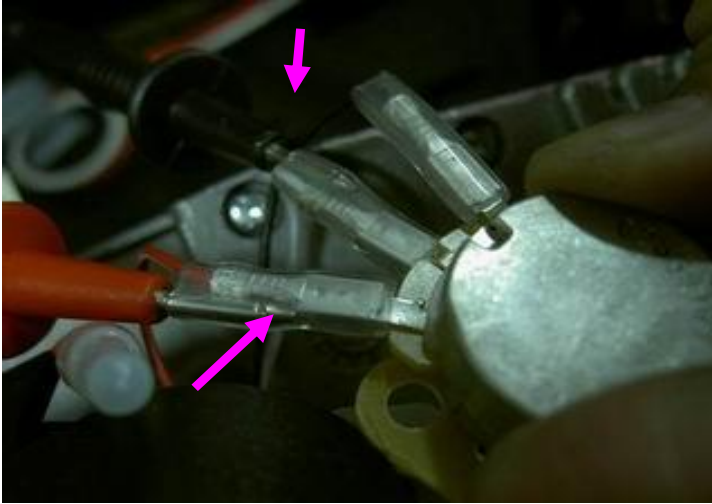
[RETURN](#)



Treadmill Trouble Shooting Guide(Error code check eliminate)

STEP 16 : Check VR (Use multimeter to check)

[RETURN](#)



STEP 17 : Use incline regulator to help treadmill back to original position.

[RETURN](#)

